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Roll No. Total Pages: 03

July-22-00433

B.Tech. EXAMINATION, 2022

Semester VII (CBCS)

INDUSTRIAL AUTOMATION AND ROBOTICS ME-701

Time: 3 Hours

Maximum Marks: 60

The candidates shall limit their answers precisely within the answer-book (40 pages) issued to them and no supplementary/continuation sheet will be issued.

Note: Attempt *Five* questions in all, selecting *one* question from each Sections A, B, C and D. Q. No. **9** is compulsory.

Section A

Are there activities in manufacturing operations that can't be automated? Explain. Describe the differences between hard and soft automation.

- 2. (b) "Robotics is an integral part of Modern manufacturing process." Justify this statement. 5
 - (b) Define term end effectors. What factors should be embodied in the design of end effectors for use in industrial robots?

 5

Section B

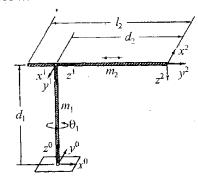
- Classify the robots according to the coordinates of motion, with a sketch and example; explain the features of each type.
- 4. What are the factors that might affect the repeatability of a manipulator? Explain. Make a list of additional factors that affect the accuracy of a manipulator. 10

Section C

Find a numerical example which shows that the order in which a rotation and a translation are performed does affect the final relationship between two initially coincident coordinates frames. Specify the coordinate transformation matrices and sketch the sequence of positions.

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6. Find the total energy of the polar coordinates robot shown below.



Section D

- Discuss various difficulties associated with the inverse kinematic solution and explain 'geometric approach' used in inverse kinematic problem.
- 8. Explain the inverse kinematics of a five axis articulated robot.

(Compulsory Question)

- 9. Write short notes on the following: $4\times5=20$
 - (a) Transfer machines for assembly
 - (b) Motion control methods
 - (c) Homogeneous transformation matrices
 - (d) Economics of robotics.